

SPECIFICATIONS:	
STEPS PER REVOLUTION: 200	ROTOR INERTIA: 460 G-CM ² (6.51E-03 oz-in-sec ²)NOM
STEP ANGLE: 1.8°	DETENT TORQUE: 0.070 N-m (9.91 oz-in) MIN
STEP TO STEP ACCURACY: ±.09 DEGREES [1], [2]	INSULATION CLASS: B
RADIAL PLAY: 0.02 mm MAX W/.5KG RADIAL LOAD	WEIGHT: 1.0 KG (2.2 LB)
TEMP. RISE: 80 °C MAX. [8]	OPERATING TEMP. RANGE: -20 TO +50 °C
RELATIVE HUMIDITY RANGE: 15 TO 85 %	STORAGE TEMP. RANGE: -30 TO +70 °C

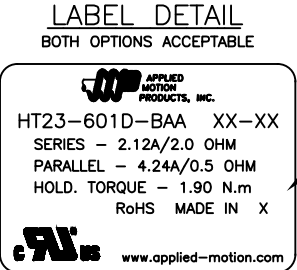
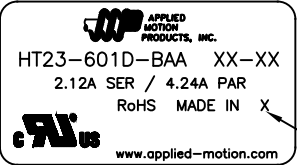
	[3]	[7]	[1]	[1]
CONNECTION	RESISTANCE PER PHASE OHM ±10%	INDUCTANCE PER PHASE mH ±20%	RATED CURRENT Amp	HOLDING TORQUE N-m Min oz-in Min
BI-POLAR SERIES	2.0	6.8	2.12	1.90 269
BI-POLAR PARALLEL	0.5	1.7	4.24	1.90 269
UNI-POLAR	1.0	1.7	3.00	1.35 191

HT23-601D-BAA

REVISIONS				
ECO NO.	REV	DESCRIPTION	DATE	APPROVED
7747	A	INITIAL RELEASE	12/20/17	J.KORDIK

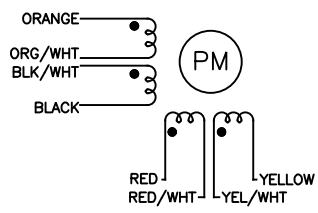
NOTES, UNLESS OTHERWISE SPECIFIED:

- [1] MEASUREMENTS MADE AT RATED CURRENT IN BOTH PHASES.
- [2] BETWEEN ANY TWO ADJACENT FULL STEP POSITIONS.
- [3] MEASUREMENTS MADE AT LEAD ENDS.
- 4. HIPOT 500 VAC, 60 Hz FOR ONE MINUTE.
- [5] LEADS: 8, 22 AWG, 7 STRAND MIN., UL AND CSA APPROVED, UL 1430 OR UL 3265.
- 6. INSULATION RESISTANCE: 100 MEGOHMS MIN AT 500 VDC.
- [7] AS MEASURED ACROSS ANY WINDING USING AN A.C. INDUCTANCE BRIDGE, AT 1 kHz. MEASUREMENTS MADE AT LEAD ENDS.
- [8] AS MEASURED BY THE CHANGE IN RESISTANCE METHOD, WITH RATED VOLTAGE APPLIED TO 2 PHASES; WITH MOTOR AT REST.
- [9] ENCODER 970-1028 INSTALLED PER AMP ASSEMBLY PRACTICES. ENCODER CABLE SOLD SEPARATELY.
- 10. THIS MOTOR IS MANUFACTURED IN COMPLIANCE WITH THE CURRENT EU RoHS DIRECTIVE.
- [11] MOTOR LABEL TO INCLUDE "ROHS" COMPLIANT, 'MADE IN (COUNTRY OF ORIGIN)' AND DATE CODE.
- 12. OTHER TAPPED HOLES MAY BE PRESENT ON REAR OF MOTOR.



[11]

WIRING DIAGRAM



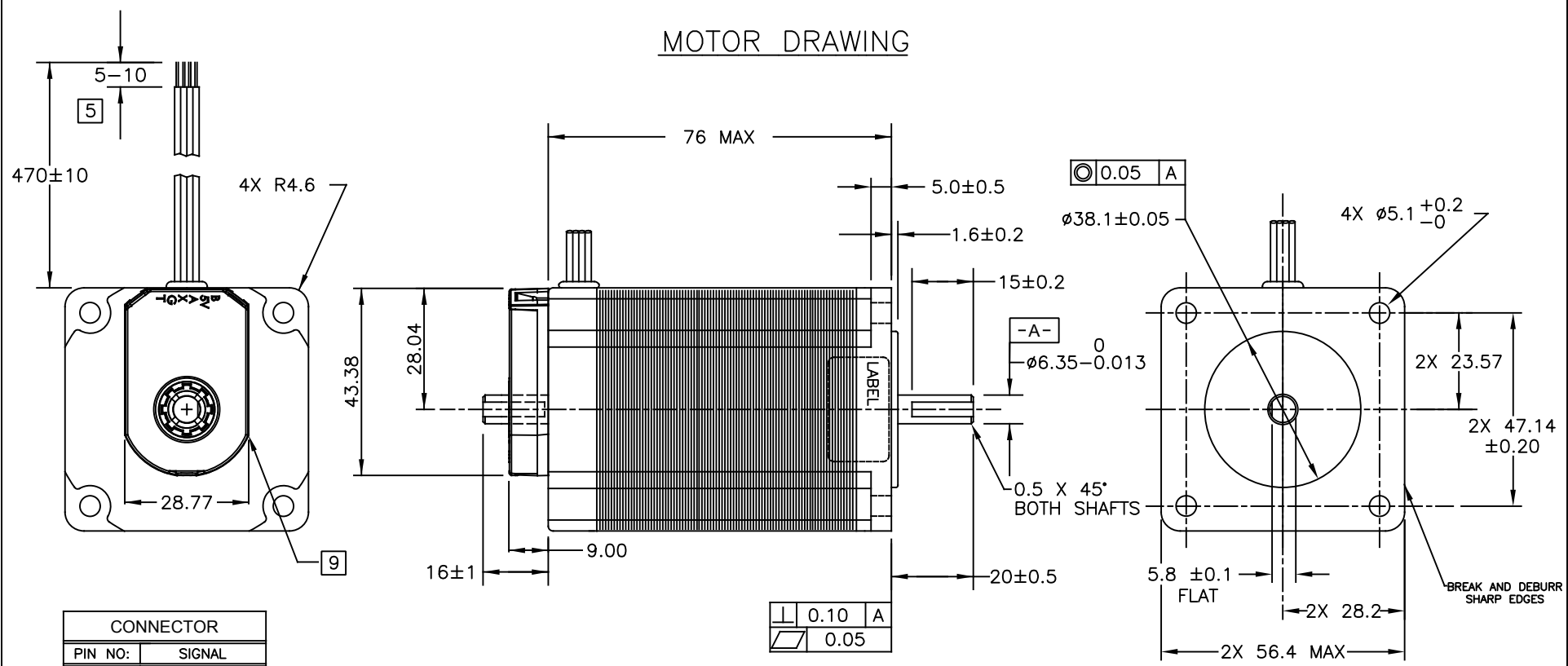
BI-POLAR, FULL STEP, 2 PHASE ON

STEP	ORANGE & BLK/WHT	BLACK & ORG/WHT	RED & YEL/WHT	YELLOW & RED/WHT
0	+	-	+	-
1	-	+	+	-
2	-	+	-	+
3	+	-	-	+
4	+	-	+	-

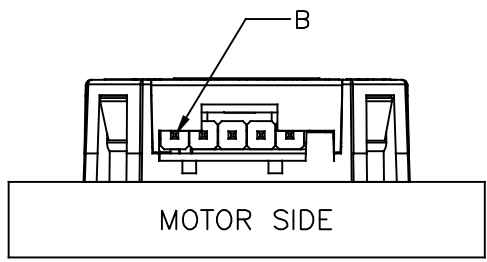
SWITCHING SEQUENCE FOR ROTATION FACING MOUNTING END.

CONTRACT NO.					
APPROVALS	DATE				
DRAWN <i>N.DEY</i>	10/25/17	<p style="text-align: center;">STEP MOTOR OUTLINE</p>			
CHECKED <i>K.KESLER</i>	12/20/17				
APPROVED <i>J.KORDIK</i>	12/20/17				
APPROVED		B	COMPUTER DATA BASE DRAWING	DWG NO. HT23-601D-BAA	REV A
SCALE: NONE		SHEET 1 OF 2			

MOTOR DRAWING



CONNECTOR	
PIN NO:	SIGNAL
B	B CHANNEL
5V	+5 V
A	A CHANNEL
X	INDEX CHANNEL
G	GND
T	UNUSED



\perp	0.10	A
∇	0.05	

TOLERANCES		THIRD ANGLE PROJECTION		APPLIED MOTION PRODUCTS, INC.	
DECIMALS: MM X.XXX = ± 0.013 X.XX = ± 0.25 X.X = ± 2.5 ANGLES: MACH. = $\pm 5^\circ$ CHAM. = $\pm 5^\circ$					
COMPUTER DATA BASE DRAWING		APPROVALS	DATE		
		DRAWN <i>N. DEY</i>	10/25/17	SCALE: 7:10	
		CHECKED <i>K. KESLER</i>	12/20/17	SHEET 2 OF 2	
		APPROVED <i>J. KORDIK</i>	12/20/17		